

#### How to count in hierarchical landscapes complexity in the mixed spherical models

Jaron Kent-Dobias INFN Sezione di Roma I

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## What landscapes?

Gaussian random functions H on the N-dimensional hypersphere with

$$\overline{H(\boldsymbol{s})H(\boldsymbol{\sigma})} = \frac{1}{N}f\left(\frac{\boldsymbol{s}\cdot\boldsymbol{\sigma}}{N}\right)$$

Important to

- Mean-field glass and spin-glass physics (pure and mixed spherical models)
- Inference applied to signal detection (*spiked tensor model*)

This talk: mixed p + s models of the form

$$f(q)=rac{1}{2}[\lambda q^p+(1-\lambda)q^s]$$



Number of points given by integral

$$\mathcal{N}(E,\mu) = \int d
u(s \mid E,\mu) \sim e^{N\Sigma(E,\mu)}$$

over Kac-Rice measure

$$d\nu(s \mid E, \mu) = \overbrace{\delta(\nabla H(s)) \mid \text{det Hess } H(s)]}^{\text{All stationary points...}} \underbrace{\delta(H(s) - NE)}_{\text{with energy density } E} \underbrace{\delta(\text{Tr Hess } H(s) - N\mu)}_{\text{and stability } \mu.}$$

$$\underbrace{\sum_{\text{`quenched' average}}}_{\text{`quenched' average}} \underbrace{\sum_{a} = \frac{1}{N} \log \overline{\mathcal{N}(E, \mu)}}_{\text{`annealed' average}}$$

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Type of point controlled by the *stability* 

$$\mu = rac{1}{N}$$
 Tr Hess  $H(s^*)$ 

For  $\mu < \mu_{\rm m},$  stationary points are saddles with varying index

For  $\mu>\mu_{\rm m},$  stationary points are minima with varying stiffness



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After manipulations, (quenched) complexity given by integral over three  $n \times n$  matrix order parameters (and two scalar order parameters)

$$\Sigma(E,\mu) = \frac{1}{N} \lim_{n \to 0} \frac{\partial}{\partial n} \int dC \, dR \, dD \, d\hat{\beta} \, d\hat{\mu} \, e^{nNS(C,R,D,\hat{\beta},\hat{\mu})}$$

C, R, D describe clustering structure of stationary points with (E,  $\mu$ )

$$\begin{split} \mathcal{S}(C,R,D,\hat{\beta},\hat{\mu}) &= \mathcal{D}(\mu) + \hat{\beta}E - \frac{1}{2}\hat{\mu} + \frac{1}{n}\left(\frac{1}{2}\hat{\mu}\operatorname{Tr}C - \mu\operatorname{Tr}R\right) \\ &+ \frac{1}{2}\sum_{ab}\left[\hat{\beta}^{2}f(C_{ab}) + (2\hat{\beta}R_{ab} - D_{ab})f'(C_{ab}) + R_{ab}^{2}f''(C_{ab})\right] + \frac{1}{2}\ln\det\begin{bmatrix}C & iR\\ iR & D\end{bmatrix} \end{split}$$

Evaluating integral by method of steepest descent requires finding saddles of  ${\mathcal S}$ 

# **HIGH PEAKS**

There is an exact correspondence between zero-temperature limit of equilibrium and ground state of complexity:

$$\lim_{T \to 0} Q \quad \Longleftrightarrow \quad \lim_{E \to E_{gs}} [C, D, R, \hat{\beta}, \hat{\mu}]$$

If Q is kRSB then C, D, R are (k-1)RSB



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Example: 3 + 16 model with 2RSB equilibrium. Annealed complexity predicts *saddles* at ground state, not minima.

Quenched complexity predicts 1RSB clustering among certain minima and saddles, consistent ground state

A Crisanti and L Leuzzi, "Amorphous-amorphous transition and the two-step replica symmetry breaking phase", Physical Review B 76, 184417 (2007)

JK-D and J Kurchan, "How to count in hierarchical landscapes: a full solution to mean-field complexity", Physical Review E 107, 064111 (2023)



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Example: 2 + 4 model with full RSB equilibrium.

Quenched complexity predicts full RSB clustering among certain minima and saddles, marginal ground state.

A Crisanti and L Leuzzi, "Spherical 2 + p spin-glass model: an exactly solvable model for glass to spin-glass transition", Physical Review Letters 93, 217203 (2004)

JK-D and J Kurchan, "How to count in hierarchical landscapes: a full solution to mean-field complexity", Physical Review E 107, 064111 (2023)







## Clustering among saddles



Many models' ground state correctly described by annealed complexity

Quenched complexity shows most clustering among *saddles* 

Can RSB arise when equilibrium is trivial?





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## How to find RSB saddles

1RSB complexity has two order parameters:

- the tightness of clustering q<sub>1</sub>
- the fraction of unclustered pairs x

On red transition line x = 1 and  $0 < q_1 \leq 1$ 

At the critical endpoint x = 1 and  $q_1 = 1$ 

Can search for critical endpoint from the annealed solution by studying eigenvalues of

$$M = \lim_{x \to 1} \lim_{q_1 \to 1} \begin{bmatrix} \frac{\partial^2 S}{\partial q_1^2} & \frac{\partial^2 S}{\partial x \partial q_1} \\ \frac{\partial^2 S}{\partial x \partial q_1} & \frac{\partial^2 S}{\partial x^2} \end{bmatrix}$$





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## Finding RSB saddles

RSB structure among saddles when  $G_f > 0$  for explicit functional  $G_f$ 

3 + s models  $f(q) = \frac{1}{2} [\lambda q^3 + (1 - \lambda)q^s]$ have a broad range of RSB among saddles

Includes models where clustering among equilibrium states is forbidden (convex  $\chi(q) = f''(q)^{-1/2}$ )

JK-D, "When is the average number of saddle points typical?", (2023), arXiv:2306.12752v1 [cond-mat.stat-mech]



## RSB among saddles: example

3 + 5 model is forbidden from having clustering between equilibrium states (at most 1RSB equilibrium order)

Wide range of saddles with highest and lowest index show clustering

Implications for emergence of RSB in equilibrium: splitting of states occurs among saddles, not minima

JK-D, "When is the average number of saddle points typical?", (2023), arXiv:2306.12752v1 [cond-mat.stat-mech]

















## Importance of marginal minima

## Quench dynamics asymptotically approaches marginal minima

In mixed models, the final energy depends on initial conditions

Threshold energy of Cugliandolo–Kurchan (where most stationary points are marginal) appears unimportant

G Folena, S Franz, and F Ricci-Tersenghi, "Rethinking mean-field glassy dynamics and its relation with the energy landscape: the surprising case of the spherical mixed *p*-spin model", Physical Review X 10, 031045 (2020)

G Folena and F Zamponi, "On weak ergodicity breaking in mean-field spin glasses", (2023), arXiv:2303.00026v2 [cond-mat.dis-nn]



## Two-point complexity

Compare different marginal minima by their local neighborhoods: what other stationary points are they nearby?

$$egin{split} \Sigma_{12} &= rac{1}{N} \int rac{d
u(\pmb{\sigma} \mid E_0, \mu_0)}{\int d
u(\pmb{\sigma}' \mid E_0, \mu_0)} \ & imes \log\left[\int d
u(\pmb{s} \mid E_1, \mu_1)\,\delta(\pmb{Nq} - \pmb{\sigma}\cdot \pmb{s})
ight] \end{split}$$

Gives complexity of stationary points with  $(E_1, \mu_1)$  constrained at overlap q with a reference point with  $(E_0, \mu_0)$ 



Properties pivot around debunked threshold  $E_{\rm th}$ 

**Below**  $E_{th}$ : Neighbors are distant minima, other marginal minima are distant

At  $E_{th}$ : Neighbors are other marginal minima, arbitrarily close together

Above  $E_{th}$ : Neighbors are close saddles, other marginal minima are distant

Suggests that typical marginal minima are far apart and separated by high barriers: no 'manifold'



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## Conclusions

Mixed spherical models have rich geometric structure not present in pure ones

- Clustering of deep minima consistent with hierarchical equilibrium order
- Clustering of saddles without any clustering of minima
- Marginally stable minima without a marginal manifold

JK-D and J Kurchan, "How to count in hierarchical landscapes: a full solution to mean-field complexity", Physical Review E **107**, 064111 (2023)

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#### Quenched complexity of mean-field models Details of calculation

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$$ig|\det ext{Hess}\, H(s_{a})ig|\,\deltaig(\operatorname{\mathsf{Tr}}\, ext{Hess}\, H(s_{a})-N\muig)\simeq e^{N\mathcal{D}(\mu)}\deltaig(N\mu-s_{a}\cdot\partial H(s_{a})ig)$$

$$\prod_{a=1}^{n} \delta(\nabla H(s_a)) \,\delta(NE - H(s_a)) = \prod_{a=1}^{n} \int d\hat{\beta} \,d\hat{s}_a \,e^{i\hat{s}_a \cdot \nabla H(s_a) + i\hat{\beta}(NE - H(s_a))}$$

$$C_{ab} = \frac{1}{N} \mathbf{s}_a \cdot \mathbf{s}_b \qquad \qquad R_{ab} = -i\frac{1}{N} \hat{\mathbf{s}}_a \cdot \mathbf{s}_b \qquad \qquad D_{ab} = \frac{1}{N} \hat{\mathbf{s}}_a \cdot \hat{\mathbf{s}}_b$$

$$S = \mathcal{D}(\mu) + \hat{\beta}E - \frac{1}{2}\hat{\mu} + \lim_{n \to 0} \frac{1}{n} \left(\frac{1}{2}\hat{\mu}\operatorname{Tr}C - \mu\operatorname{Tr}R\right)$$
$$+ \frac{1}{2}\sum_{ab} \left[\hat{\beta}^{2}f(C_{ab}) + (2\hat{\beta}R_{ab} - D_{ab})f'(C_{ab}) + R_{ab}^{2}f''(C_{ab})\right] + \frac{1}{2}\ln\det\begin{bmatrix}C & iR\\ iR & D\end{bmatrix}$$

#### Quenched complexity of mean-field models RS-FRSB transition line



RS-FRSB transition line can be analytically predicted.

- 1. Treat each function c(x), r(x), d(x) as piecewise linear
- 2. Substitute into  $\Sigma$  and expand for small  $x_{max}$
- 3. Look for instability of  $x_{max} = 0$  solution.

$$\mu_{\pm}(E) = \pm \frac{(f'(1) + f''(0))(f'(1)^2 - f(1)(f'(1) + f''(1)))}{(2f(1) - f'(1))f'(1)f''(0)^{1/2}} - \frac{f''(1) - f'(1)}{f'(1) - 2f(1)}E$$

## Finding RSB saddles

Endpoint (and therefore RSB saddles) exists when  $G_f > 0$  for

$$G_{f} = f' \log \frac{f''}{f'} \left[ 3y_{f}(f''-f')f'''-2(f'-2f)f''w_{f} \right] - 2(f''-f')u_{f}w_{f} - 2\log^{2}\frac{f''}{f'}f'^{2}f''v_{f}$$

where

$$= f(f' + f'') - f'^{2} \qquad v_{f} = f$$
  
=  $2f''(f'' - f') + f'f''' \qquad y_{f} = f$ 

$$egin{aligned} &V_f = f'(f''+f''') - f''^2 \ &V_f = f'(f'-f) + f''f \end{aligned}$$

For 3 + s models with  $f(q) = \frac{1}{2} [\lambda q^3 + (1 - \lambda)q^s]$ , very broad range have RSB saddles

 $u_f =$  $w_f =$ 

Includes models where clustering among equilibrium states is forbidden (convex  $\chi(q) = f''(q)^{-1/2}$ )

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## Range of saddle clustering

Clustering among saddles found for most 3 + s models with  $s \ge 5$  and broad range of energies

Phase crosses into minima consistent with presence of RSB ground states





Below the threshold energy



At the threshold energy



Above the threshold energy

